

# Metadata

Field	Value
<b>Data Collector</b>	Harasyn, Madison
<b>Deployment ID</b>	July 27th 2019
<b>Research Area</b>	churchill
<b>Deployment Dates</b>	
<b>Location or Station ID</b>	Churchill, Manitoba
<b>Instrument Details</b>	
<b>Instrument Details 1</b>	
<b>Instrument Name</b>	Matrice 200 Series V2/DJI M210 RTK
<b>Standardized Instrument Name</b>	
<b>Instrument Unique ID</b>	
<b>Instrument DOI</b>	DOI
<b>Description</b>	DJI Matrice 210 quadcopter drone/RPAS, real-time kinematic. A tethered drone with a DJI Zenmuse Z30 optical video camera.
<b>Instrument Details 2</b>	
<b>Instrument Name</b>	DJI Zenmuse Z30

Field	Value
<b>Standardized Instrument Name</b>	cameras
<b>Instrument Unique ID</b>	
<b>Instrument DOI</b>	DOI
<b>Description</b>	An optical photo and video camera to mount to a DJI compatible drone, has a 30x optical zoom.
<b>Related Files</b>	

## Data and Resources

Field	Value
<b>URL</b>	<a href="https://canwin-datahub.ad.umanitoba.ca/data/dataset/2f3631e0-419d-4565-81b0-24ad63465939/resource/64faff9b-5e67-40b3-a58a-659f2f6f9437/download/canwin_deployment_metadataahasyn.docx">https://canwin-datahub.ad.umanitoba.ca/data/dataset/2f3631e0-419d-4565-81b0-24ad63465939/resource/64faff9b-5e67-40b3-a58a-659f2f6f9437/download/canwin_deployment_metadataahasyn.docx</a>
<b>Name</b>	July 27th 2019 Churchill Drone - Deployment Description
<b>Description</b>	Deployment information in the (.docx) file is related to the July 27th, 2019 Churchill drone deployment of the Matrice 200 Series V2/M210 RTK unmanned aerial vehicle (UAV) in the Churchill Estuary. The UAV was fitted with a compatible DJI Zenmuse 30 camera to capture videos of belugas and boats.
<b>Format</b>	DOCX
<b>Resource Category</b>	supplemental

## Related Datasets

Field	Value
<b>Title</b>	Churchill Beluga Boat Drone Imagery
<b>URL</b>	<a href="https://canwin-datahub.ad.umanitoba.ca/data/dataset/churchill-beluga-boat-drone-imagery">https://canwin-datahub.ad.umanitoba.ca/data/dataset/churchill-beluga-boat-drone-imagery</a>